

Data Structures and Algorithms

(CS210A)

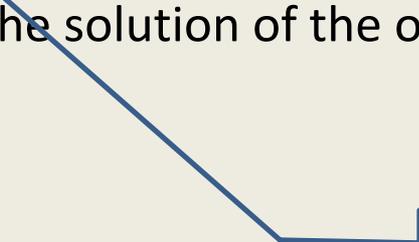
Lecture 15:

- Algorithm paradigm of **Divide and Conquer** :
 Counting the number of Inversions
- Another sorting algorithm based on **Divide and Conquer** : **Quick Sort**

Divide and Conquer paradigm

An Overview

1. **Divide** the problem instance into two or more instances of the same problem
2. Solve each smaller instances recursively (base case suitably defined).
3. **Combine** the solutions of the smaller instances to get the solution of the original instance.



This is usually the main **nontrivial** step in the design of an algorithm using divide and conquer strategy

2 IMPORTANT LESSONS

THAT WE WILL LEARN TODAY...

1. Role of **Data structures** in **algorithms**
2. Learn from the **past** ...

Role of Data Structures in designing efficient algorithms

Definition: A collection of data elements *arranged and connected* in a way which can facilitate efficient executions of a (possibly long) sequence of operations.

Parameters:

- Query/Update time
- Space
- Preprocessing time

Role of Data Structures in designing efficient algorithms

Definition: A collection of data elements *arranged and connected* in a way which can facilitate efficient executions of a (possibly long) sequence of operations.

Consider an Algorithm **A**.

Suppose **A** performs many operations of **same type** on some data.

Improving time complexity of these operations



Improving the time complexity of **A**.

So, it is worth designing a suitable **data structure**.

Counting Inversions in an array

Problem description

Definition (Inversion): Given an array **A** of size **n**, a pair (i,j) , $0 \leq i < j < n$ is called an inversion if $A[i] > A[j]$.

Example:

	0	1	2	3	4	5	6	7
A	3	15	8	19	9	67	11	27

Inversions are :

$(1,2), (1,4), (1,6),$

$(3,4), (3,6),$

$(5,6), (5,7)$

AIM: An efficient algorithm to count the number of inversions in an array **A**.

Counting Inversions in an array

Problem familiarization

Trivial-algo($A[0..n-1]$)

{ count \leftarrow 0;

For($j=1$ to $n-1$) do

{ For($i=0$ to $j-1$)

{ If ($A[i] > A[j]$) count \leftarrow count + 1;

}

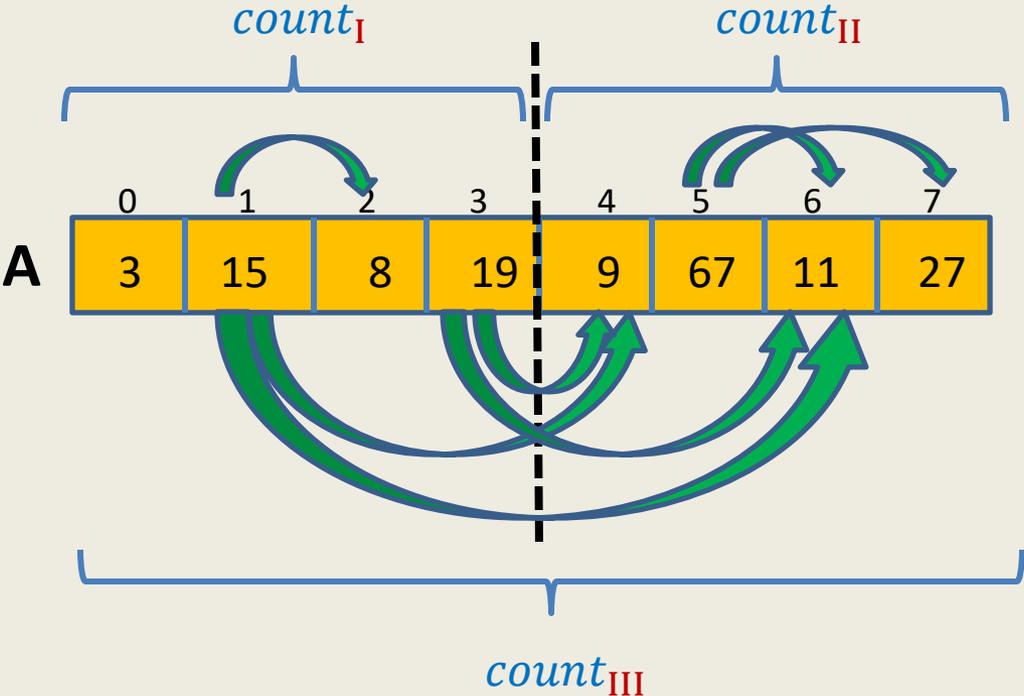
} return count;

}

Time complexity: $O(n^2)$

Let us try to design a
Divide and Conquer based algorithm

How do we approach using **divide & conquer**



Counting Inversions

Divide and Conquer based algorithm

CountInversion(**A**, **i**, **k**) // Counting no. of inversions in **A**[**i**..**k**]

If (**i** = **k**) return 0;

Else{ **mid** ← (**i** + **k**)/2;

$count_I \leftarrow \text{CountInversion}(\mathbf{A}, \mathbf{i}, \mathbf{mid});$

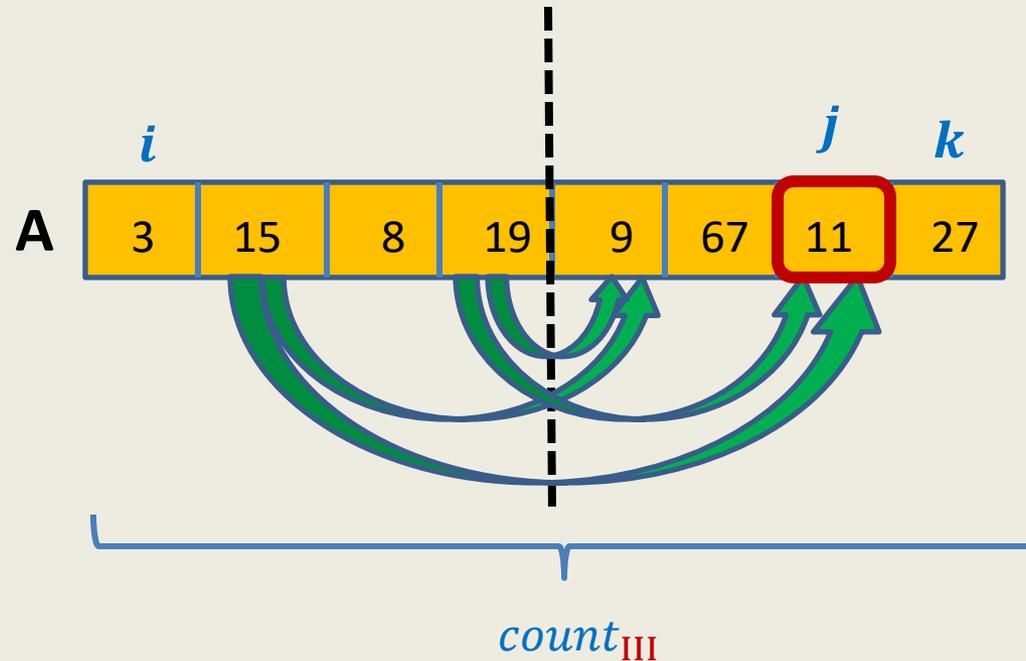
$count_{II} \leftarrow \text{CountInversion}(\mathbf{A}, \mathbf{mid} + 1, \mathbf{k});$

.... Code for $count_{III}$

return $count_I + count_{II} + count_{III}$;

}

How to efficiently compute $count_{III}$ (Inversions of type III) ?



$O(n^2)$ time algo

Aim: For each $mid < j \leq k$, count the elements in $A[i..mid]$ that are **greater** than $A[j]$.

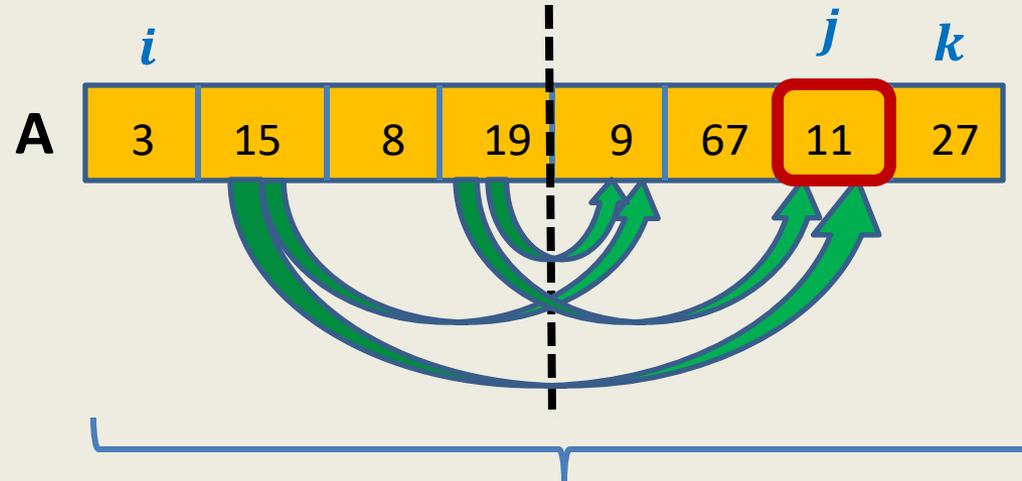
Trivial way: $O(\text{size of the subarray } A[i..mid])$ time for a given j .

→ $O(n)$ time for a given j in the first call of the algorithm.

→ $O(n^2)$ time for computing $count_{III}$ since there are $n/2$ possible values of j .

How to efficiently compute $count_{III}$ (Inversions of type III) ?

Let us state clearly what we want to achieve ...



For each $j \in [mid + 1, k]$

count the elements in $A[i..mid]$ that are **greater** than $A[j]$.

Time to apply Lesson 1

What should be the **data structure** ?

Sorted subarray $A[i..mid]$.

Counting Inversions

First algorithm based on **divide & conquer**

CountInversion(A, i, k)

If ($i=k$) return 0;

Else{ $mid \leftarrow (i + k)/2$;

$count_I \leftarrow$ CountInversion(A, i, mid);

$count_{II} \leftarrow$ CountInversion($A, mid + 1, k$);

} $2 T(n/2)$

Sort(A, i, mid);

For each $mid < j \leq k$

do **binary search** for $A[j]$ in $A[i..mid]$ to compute the *number* of elements greater than $A[j]$.

Add this *number* to $count_{III}$;

} $c n \log n$

return $count_I + count_{II} + count_{III}$;

}

Counting Inversions

First algorithm based on **divide & conquer**

Time complexity analysis:

If $n = 1$,

$$T(n) = c \text{ for some constant } c$$

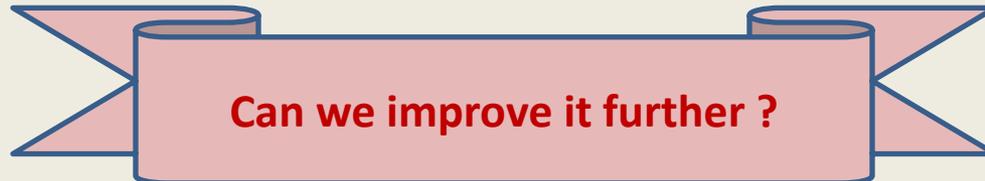
If $n > 1$,

$$T(n) = c n \log n + 2 T(n/2)$$

$$= c n \log n + c n ((\log n) - 1) + 2^2 T(n/2^2)$$

$$= c n \log n + c n ((\log n) - 1) + c n ((\log n) - 2) + 2^3 T(n/2^3)$$

$$= O(n \log^2 n)$$



Counting Inversions

First algorithm based on **divide & conquer**

CountInversion(A, i, k)

If ($i=k$) return 0;

Else{ $mid \leftarrow (i + k)/2$;

$count_I \leftarrow$ CountInversion(A, i, mid);

$count_{II} \leftarrow$ CountInversion($A, mid + 1, k$);

} $2 T(n/2)$

Sort(A, i, mid);

For each $mid < j \leq k$

do **binary search** for $A[j]$ in $A[i..mid]$ to compute the number of elements greater than $A[j]$.

Add this number to $count_{III}$;

} $c n \log n$

return $count_I + count_{II} + count_{III}$;

}

Sequence of observations

To achieve better running time

- The extra $\log n$ factor arises because for the “combine” step, we are spending $O(n \log n)$ time instead of $O(n)$.
- The reason for $O(n \log n)$ time for the “combine” step:
 - Sorting $A[0.. n/2]$ takes $O(n \log n)$ time.
 - Doing Binary Search for $n/2$ elements from $A[n/2... n-1]$
- Each of the above tasks have optimal running time.
- So the only way to improve the running time of “combine” step is some new idea

Revisiting MergeSort algorithm

MSort(A, *i*, *k*) // Sorting A[*i*.. *k*]

{ If (*i* < *k*)

{ **mid** ← (*i* + *k*)/2;

MSort(A, *i*, **mid**);

MSort(A, **mid** + 1, *k*);

Create a temporary array C[0.. *k* - *i*]

Merge(A, *i*, **mid**, *k*, C);

Copy C[0.. *k* - *i*] to A[*i*.. *k*]

}

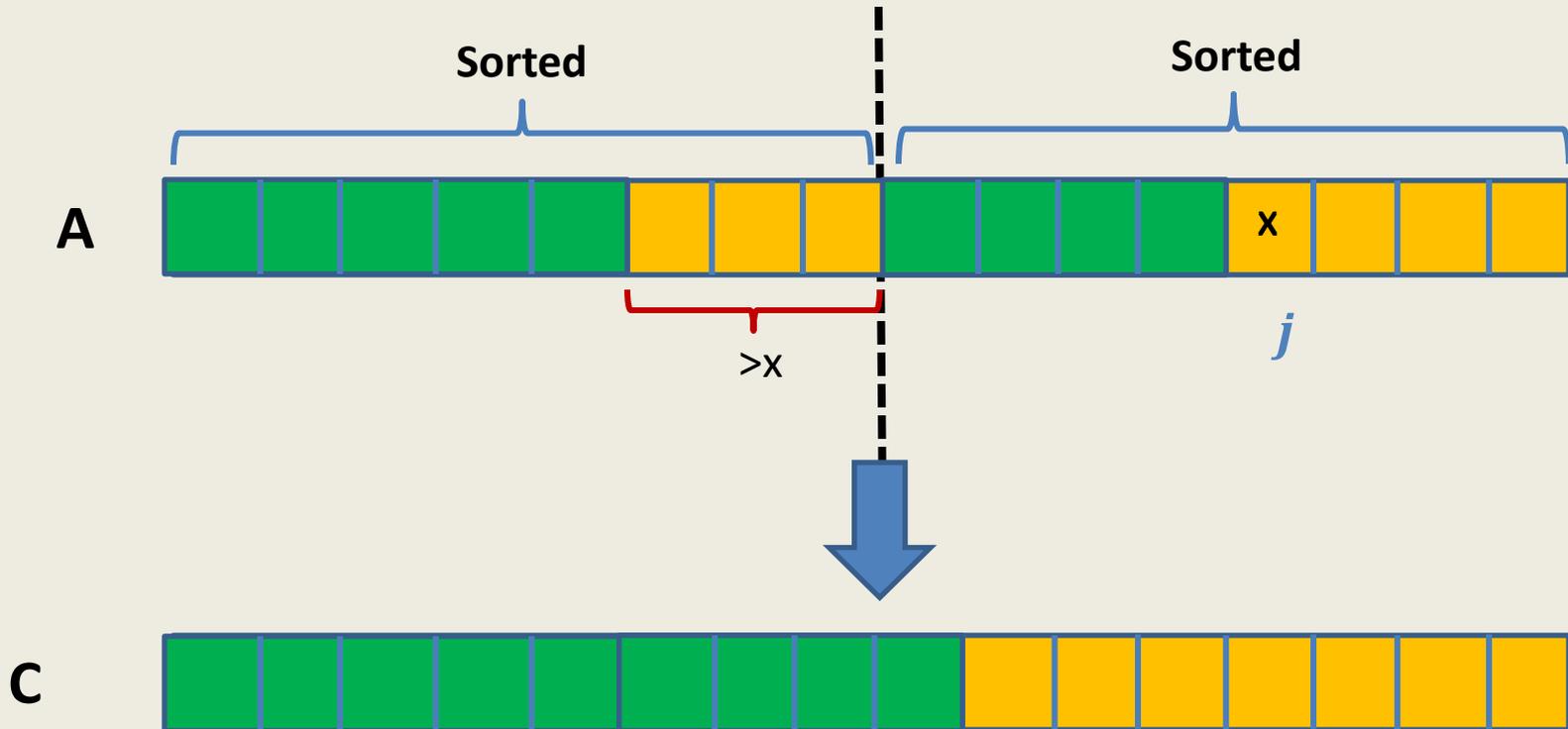
}

We shall carefully look at the **Merge()** procedure to find an efficient way to count the number of elements from A[*i*.. **mid**] which are smaller than A[*j*] for any given

$$\mathbf{mid} < j \leq k$$

Relook

Merging $A[i..mid]$ and $A[mid + 1..k]$



Pesudo-code for Merging two sorted arrays

Merge(A, i, mid, k, C)

$p \leftarrow i; j \leftarrow \text{mid} + 1; r \leftarrow 0;$

While($p \leq \text{mid}$ and $j \leq k$)

{ If($A[p] < A[j]$) { $C[r] \leftarrow A[p]; r++; p++$ }

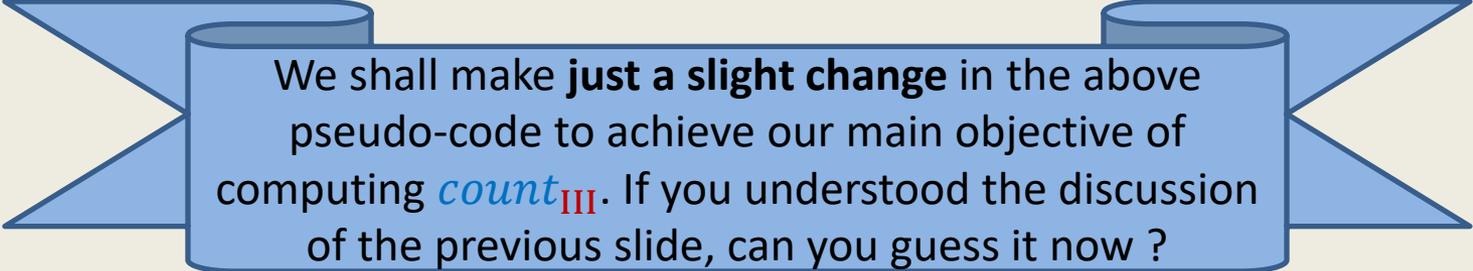
Else { $C[r] \leftarrow A[j]; r++; j++$ }

}

While($p \leq \text{mid}$) { $C[k] \leftarrow A[i]; k++; i++$ }

While($j \leq k$) { $C[k] \leftarrow A[j]; k++; j++$ }

return C ;



We shall make **just a slight change** in the above pseudo-code to achieve our main objective of computing count_{III} . If you understood the discussion of the previous slide, can you guess it now ?

Pesudo-code for Merging and counting inversions

Merge_and_CountInversion(A, i , mid , k , C)

$p \leftarrow i$; $j \leftarrow mid + 1$; $r \leftarrow 0$;

$count_{III} \leftarrow 0$;

While($p \leq mid$ and $j \leq k$)

{ If($A[p] < A[j]$) { C[r] \leftarrow A[p]; $r++$; $p++$ } }

Else { C[r] \leftarrow A[j]; $r++$; $j++$

$count_{III} \leftarrow count_{III} + (mid - p + 1)$;

}

}

While($p \leq mid$) { C[k] \leftarrow A[i]; $k++$; $i++$ }

While($j \leq k$) { C[k] \leftarrow A[j]; $k++$; $j++$ }

return $count_{III}$;

Nothing extra is
needed here.

Counting Inversions

Final algorithm based on **divide & conquer**

Sort_and_CountInversion(A, *i*, *k*)

```
{ If (i = k) return 0;
  else
  { mid ← (i + k)/2;
    countI ← Sort_and_CountInversion (A,i, mid);
    countII ← Sort_and_CountInversion (A,mid + 1, k);
    Create a temporary array C[ 0.. k - i]
    countIII ← Merge_and_CountInversion(A,i, mid, k,C);
    Copy C[0.. k - i] to A[i.. k];
    return countI + countII + countIII ;
  }
}
```

} $2 T(n/2)$
} $O(n)$

Counting Inversions

Final algorithm based on **divide & conquer**

Time complexity analysis:

If $n = 1$,

$$T(n) = c \text{ for some constant } c$$

If $n > 1$,

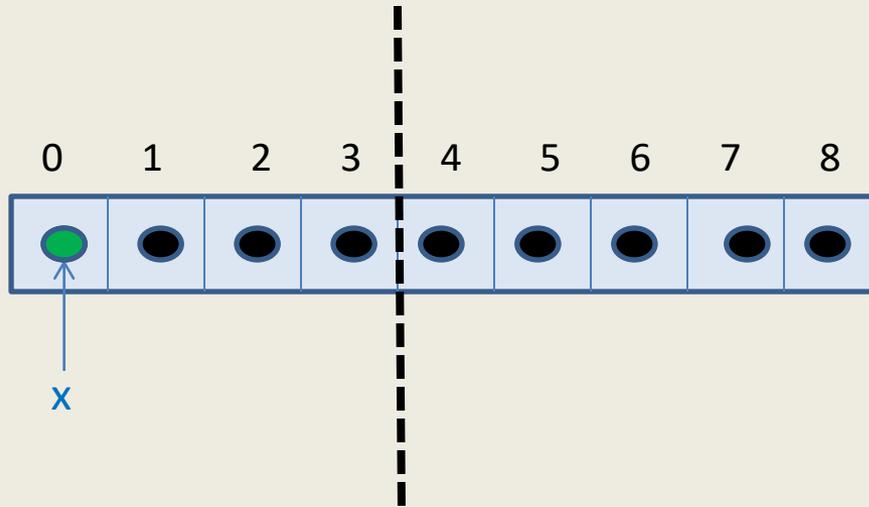
$$\begin{aligned} T(n) &= c n + 2 T(n/2) \\ &= O(n \log n) \end{aligned}$$

Theorem: There is a **divide and conquer** based algorithm for computing the number of inversions in an array of size n . The running time of the algorithm is $O(n \log n)$.

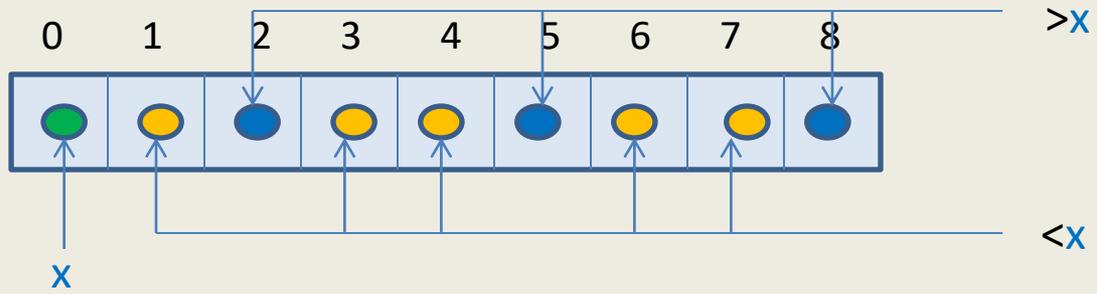
**Another sorting algorithm based on
divide and conquer**

QuickSort

Is there any alternate way to **divide** ?



In MergeSort, we divide the input instance in an obvious manner.



Pseudocode for QuickSort(S)

QuickSort(S)

{ If ($|S| > 1$)

 Pick and remove an element x from S ;

$(S_{<x}, S_{>x}) \leftarrow \text{Partition}(S, x)$;

 return(Concatenate(QuickSort($S_{<x}$), x , QuickSort($S_{>x}$)))

}

Pseudocode for QuickSort(S)

When the input S is stored in an array

QuickSort(A, l, r)

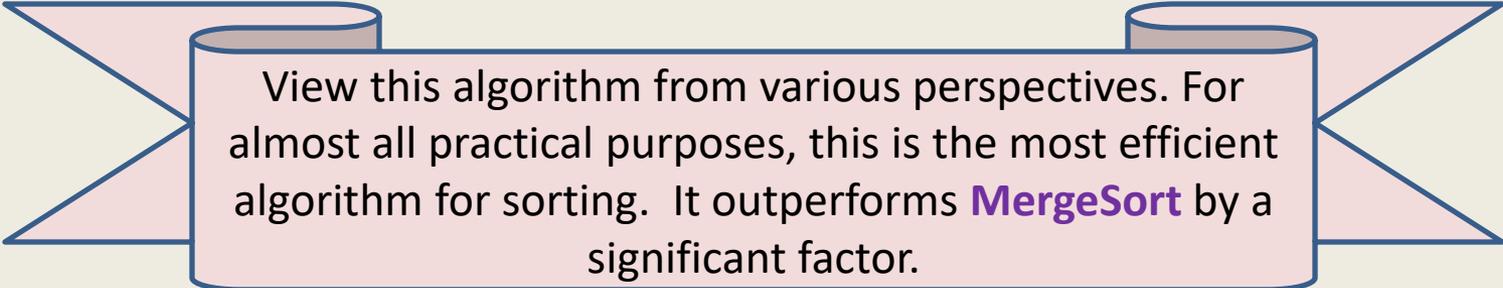
{ If ($l < r$)

$i \leftarrow$ **Partition**(A, l, r); // i is index where element $A[l]$ is finally placed

QuickSort($A, l, i - 1$);

QuickSort($A, i + 1, r$)

}



View this algorithm from various perspectives. For almost all practical purposes, this is the most efficient algorithm for sorting. It outperforms **MergeSort** by a significant factor.

QuickSort

Homework:

- The running time of Quick Sort depends upon the element we choose for partition in each recursive call.
- What can be the worst case running time of Quick Sort ?
- What can be the best case running time of Quick Sort ?
- Give an implementation of **Partition** that takes $O(r - l)$ time and using $O(1)$ extra space only. (I gave this homework last week as well)

*Sometime later in the course, we shall revisit **QuickSort** and analyze it **theoretically** (average time complexity) and **experimentally**.*

*The outcome will be **surprising** and **counterintuitive**. 😊*