Data Structures and Algorithms (CS210A) Semester I – 2014-15

Lecture 8:

Inventing a new Data Structure with

- Flexibility of lists for updates
- Efficiency of arrays for search

Important Notice

There are basically two ways of introducing a new/innovative solution of a problem. One way is to just <u>explain</u> it without giving any clue as to how the person who invented the concept came up with this solution. Another way is to start from scratch and take a journey of the route which the inventor might have followed to arrive at the solution. This journey goes through various hurdles and questions, each hinting towards a better insight into the problem if we have patience and open mind. Which of these two ways is better ?

I believe that the second way is better and more effective. The current lecture is based on this way. The data structure we shall invent is called a Binary Search Tree. This is the most fundamental and versatile data structure. We shall realize this fact many times during the course ...

Doubly Linked List based implementation versus array based implementation of "List"

Operation	Time Complexity per operation for array based implementation	Time Complexity per operation for doubly linked list based implementation	
lsEmpty(L)	O(1)	<mark>O(1)</mark>	
Search(x,L)	O (n)	O(n)	
Successor(p,L)	O(1)	<mark>O(1)</mark>	
Predecessor(p,L)	O(1)	<mark>O(1)</mark>	
CreateEmptyList(L)	O(1)	O(1)	
Insert(x,p,L)	O (n)	O(1)	
Delete(p,L)	O (n)	O(1)	
MakeListEmpty(L)	O(1)	<mark>0</mark> (1)	

Problem



Inventing a new data structure New Data structure Lists are flexible, so let us try modifying the linked list structure to achieve fast **search** time. 0 Too Rigid for updates Head Lists Array

Restructuring doubly linked list



A new data structure emerges



A new data structure emerges

To analyze it mathematically, remove irrlevant details



Nature is a great source of inspiration



Nature is a great source of inspiration



Nature is a great source of inspiration



Binary Tree: A mathematical model

Definition: A collection of nodes is said to form a binary tree if

- There is exactly one node with no incoming edge.
 This node is called the **root** of the tree.
- 2. Every node other than root node has **exactly one incoming edge**.
- 3. Each node has <u>at most two outgoing edges</u>.



Binary Tree: some terminologies

• If there is an edge from node **u** to node **v**,

then u is called parent of v ,and v is called child of u.

 The Height of a Binary tree T is the <u>maximum</u> number of edges from the root to any leaf node in the tree T.



Varieties of Binary trees



skewed

Height of a perfectly balanced Binary tree



H(n): Height of a perfectly balanced binary tree on n nodes. H(1) = 0

 $H(n) \leq 1 + H\left(\frac{n}{2}\right)$

Height of a perfectly balanced Binary tree



H(n): Height of a perfectly balanced binary tree on n nodes. H(1) = 0

$$H(n) \leq 1 + H\left(\frac{n}{2}\right)$$

$$\leq 1 + 1 + H\left(\frac{n}{4}\right)$$

$$\leq 1 + 1 + \dots + H\left(\frac{n}{2^{i}}\right)$$

$$\leq \log_{2} \frac{1}{n}$$

Implementing a Binary trees



Binary Search Tree (BST)



Definition: A Binary Tree **T** storing values is said to be Binary Search Tree if for each node **v** in T

- If left(v) <> NULL, then value(v) > value of every node in subtree(left(v)).
- If right(v)<>NULL, then value(v) < value of every node in subtree(right(v)).



Search(T,x)

Searching in a Binary Search Tree





A question

Time complexity of Search(T,x) and Insert(T,x) in a Binary Search Tree T = O(Height(T))

Homeworks

- Write pseudocode for Insert(T,x) operation similar to the pseudocode we wrote for Search(T,x).
- Design an algorithm for the following problem:

Given a <u>sorted array</u> **A** storing **n** elements, build a <u>"perfectly balanced"</u> BST storing all elements of **A** in **O**(**n**) time.

Homework 3

What does the following algorithm accomplish ? Traversal(T)

{ **p← T**;

if(p=NULL) return;

else{ if(left(p) <> NULL) Traversal(left(p));
 print(value(p));
 if(right(p) <> NULL) Traversal(right(p));

if(right(p) <> NULL) Traversal(right(p));

Ponder over this algorithm for a few minutes to know what it is doing. You might like to try it out on some example of BST. It prints the elements of pinary search tree in increasing order of their values. What is its time complexity ?

Time complexity of <u>any search</u> and <u>any single insertion</u> in a perfectly balanced Binary Search Tree on n nodes



Time complexity of <u>any search</u> and <u>any single insertion</u> in a sqewed Binary Search Tree on n nodes



Our original Problem

Maintain a telephone directory

Operations:

- Search the phone # of a person with ID no. x
- Insert a new record (ID no., phone #,...)

	Array based solution	Linked list based solution
ζ (Log n	<mark>O</mark> (n)
	<mark>O</mark> (n)	Log n

Solution : We may keep perfectly balanced BST.
Hurdle: What if we insert records in increasing order of ID ?
→ BST will be skewed ⁽²⁾

BST data structure that we invented looks very elegant, let us try to find a way to overcome the hurdle.

- Let us try to find a way of achieving **Log** *n* search time.
- Perfectly balanced BST achieve Log *n* search time.
- But the definition of Perfectly balanced BST looks <u>too</u> <u>restrictive</u>.
- Let us investigate : How crucial is perfect balance of a BST ?

How crucial is perfect balance of a BST ?

H(1) = 0 $H(n) = \leq 1 + H\left(\frac{n}{2}\right)$ Let us change this recurrence slightly. n $\leq \frac{n}{2}$ $\leq \frac{1}{2}$ n

How crucial is perfect balance of a BST ?



H(1) = 0

$$(n) \leq \mathbf{1} + H\left(\frac{3n}{4}\right)$$
$$\leq \mathbf{1} + \mathbf{1} + H\left(\left(\frac{3}{4}\right)^2 n\right)$$
$$\leq \mathbf{1} + \mathbf{1} + \dots + H\left(\left(\frac{3}{4}\right)^i n\right)$$

 $\leq \log_{4/3} n$

Lesson learnt : We may as well work with <u>nearly</u> balanced BST

Nearly balanced Binary Search Tree

Terminology:

size of a binary tree is the number of nodes present in it.

Definition: A binary search tree **T** is said to be <u>nearly balanced</u> at node **v**, if size(left(v)) $\leq \frac{3}{4}$ size(v) and size(right(v)) $\leq \frac{3}{4}$ size(v)

Definition: A binary search tree T is said to be nearly balanced if it is <u>nearly balanced</u> at each node.

Nearly balanced Binary Search Tree

Think of ways of using **nearly balanced BST** for solving our dictionary problem.

You might find the following **observations/tools** helpful :

- If a node v is perfectly balanced, it requires <u>many insertions</u> till v ceases to remain nearly balanced.
- Any arbitrary BST of size n can be converted into a perfectly balanced BST in O(n) time.

Solving our dictionary problem Preserving O(log *n*) height after each operation

Each node v in T maintains additional field size(v) which is the number of nodes in the subtree(v).

- Keep **Search(T**,**x**) operation unchanged.
- Modify Insert(T,x) operation as follows:
 - Carry out normal insert and update the size fields of nodes traversed.
 - If BST T is ceases to be nearly imbalanced at any node v, transform subtree(v) into perfectly balanced BST.

"Perfectly Balancing" subtree at a node v



What can we say about this data structure ?

It is elegant and reasonably simple to implement.

Yes, there will be huge computation for some insertion operations.

But the number of such operations will be rare.

So, at least intuitively, the data structure appears to be efficient.

Indeed, this data structure achieve the following goals:

- For any arbitrary sequence of *n* operations, total time will be O(*n* log *n*).
- Worst case search time: **O(log n)**

You will do programming assignment to verify the validity of the two claims mentioned above experimentally.

What about the theoretical analysis to justify these claims ?

Keep thinking till we do it in a few weeks \odot .